#### Optimization

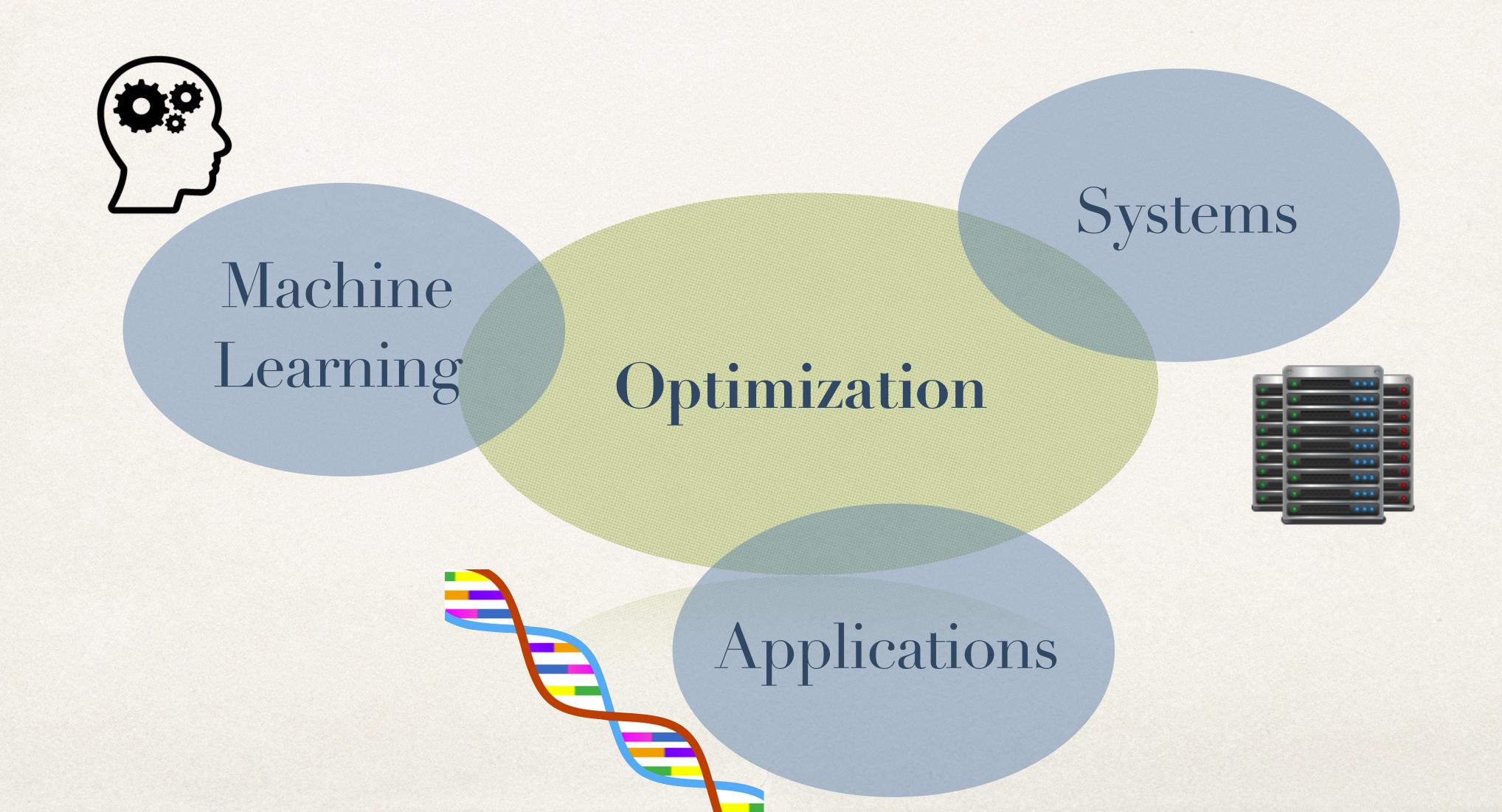
## for Machine Learning in Practice I

Martin Jaggi

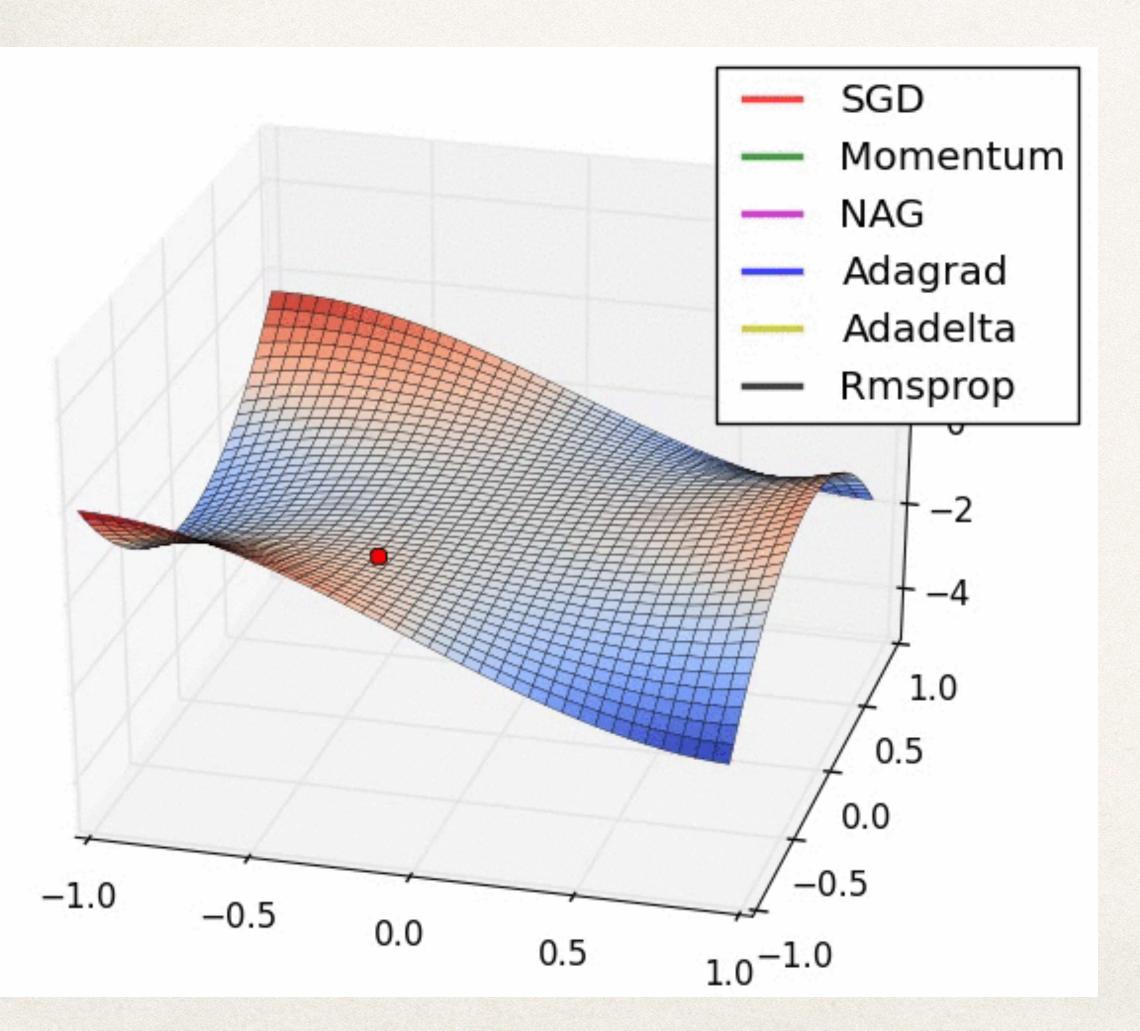


Machine Learning and Optimization Laboratory mlo.epfl.ch

#### Where are we?



## Practical comparison of algorithms



Adagrad Adadelt Rmspro

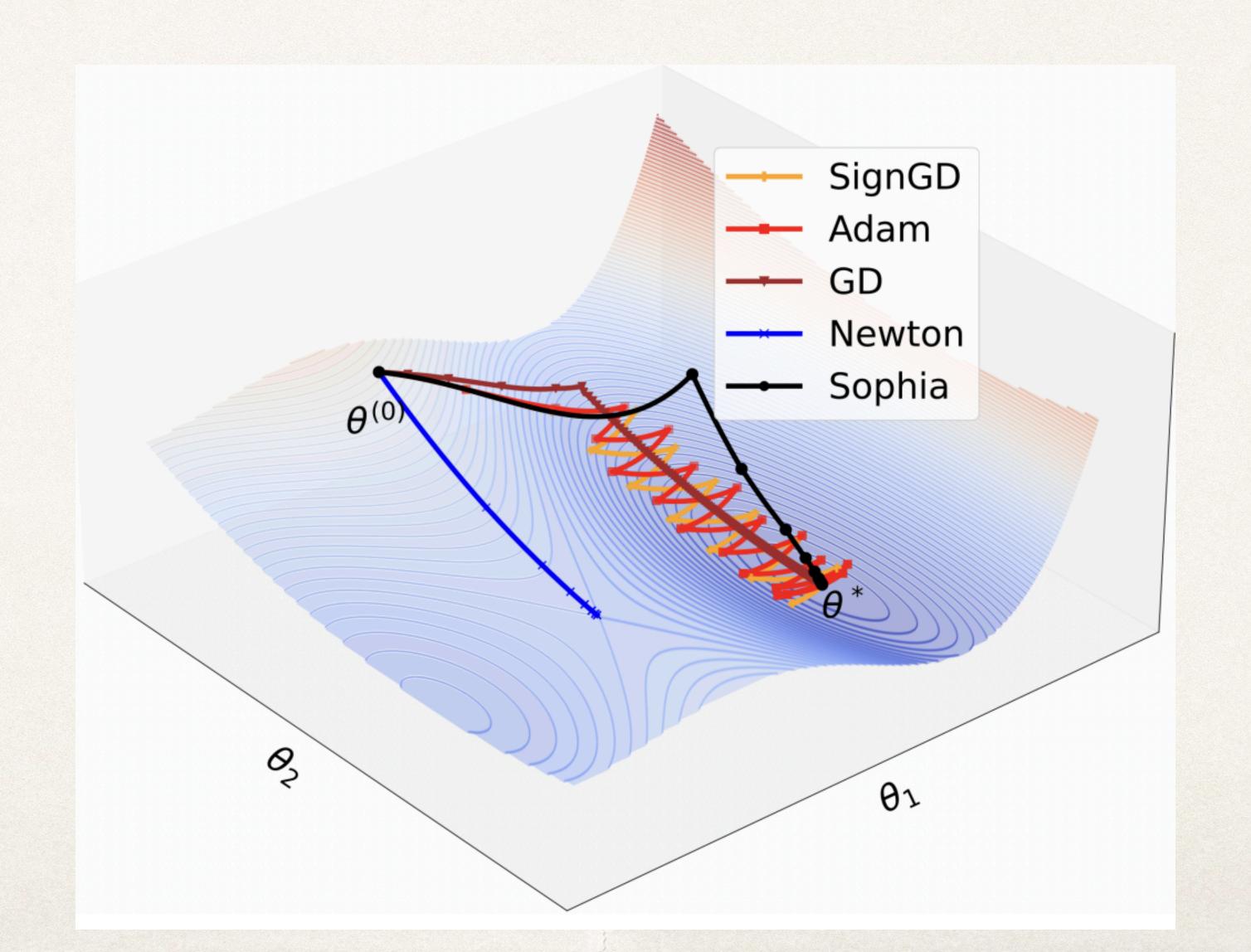
SGD

NAG

Moment

https://imgur.com/a/Hqolp#2dKCQHh

## Practical comparison of algorithms



#### Trends - General

- Custom AI hardware & systems
- \* Federated or decentralized training
- \* Privacy
- \* Interpretability
- \* trust, fairness and robustness in ML

(e.g. robust & secure against adversaries)

Optimization is a key element of most above topics

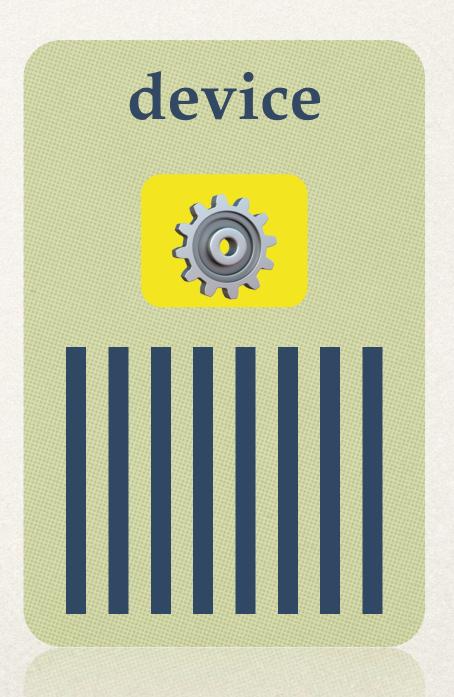
## ML Training

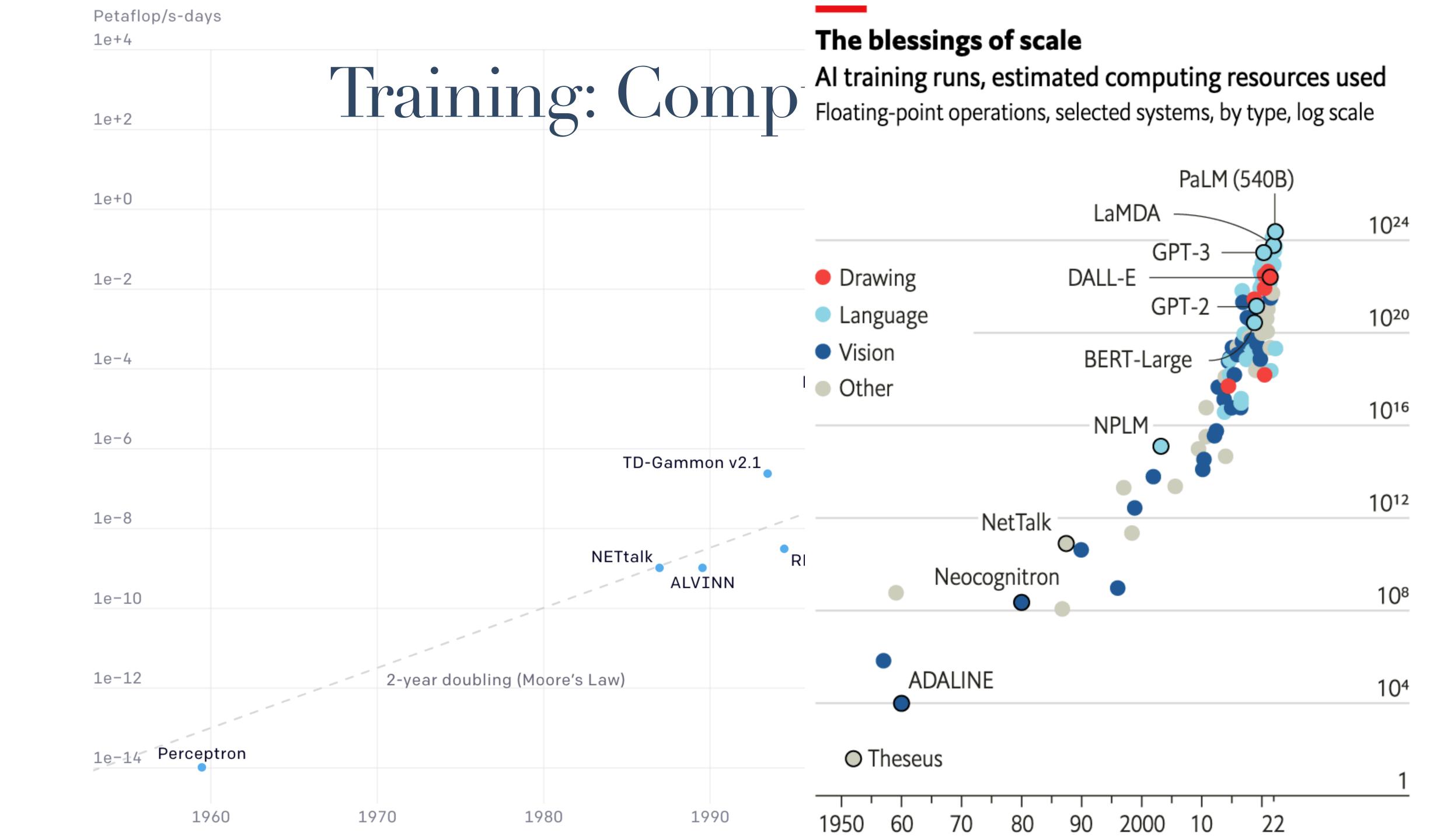
$$\min_{\mathbf{x}} f(\mathbf{x}) = \frac{1}{|data|} \sum_{i \in data} f_i(\mathbf{x})$$

#### Training algorithms: SGD-based

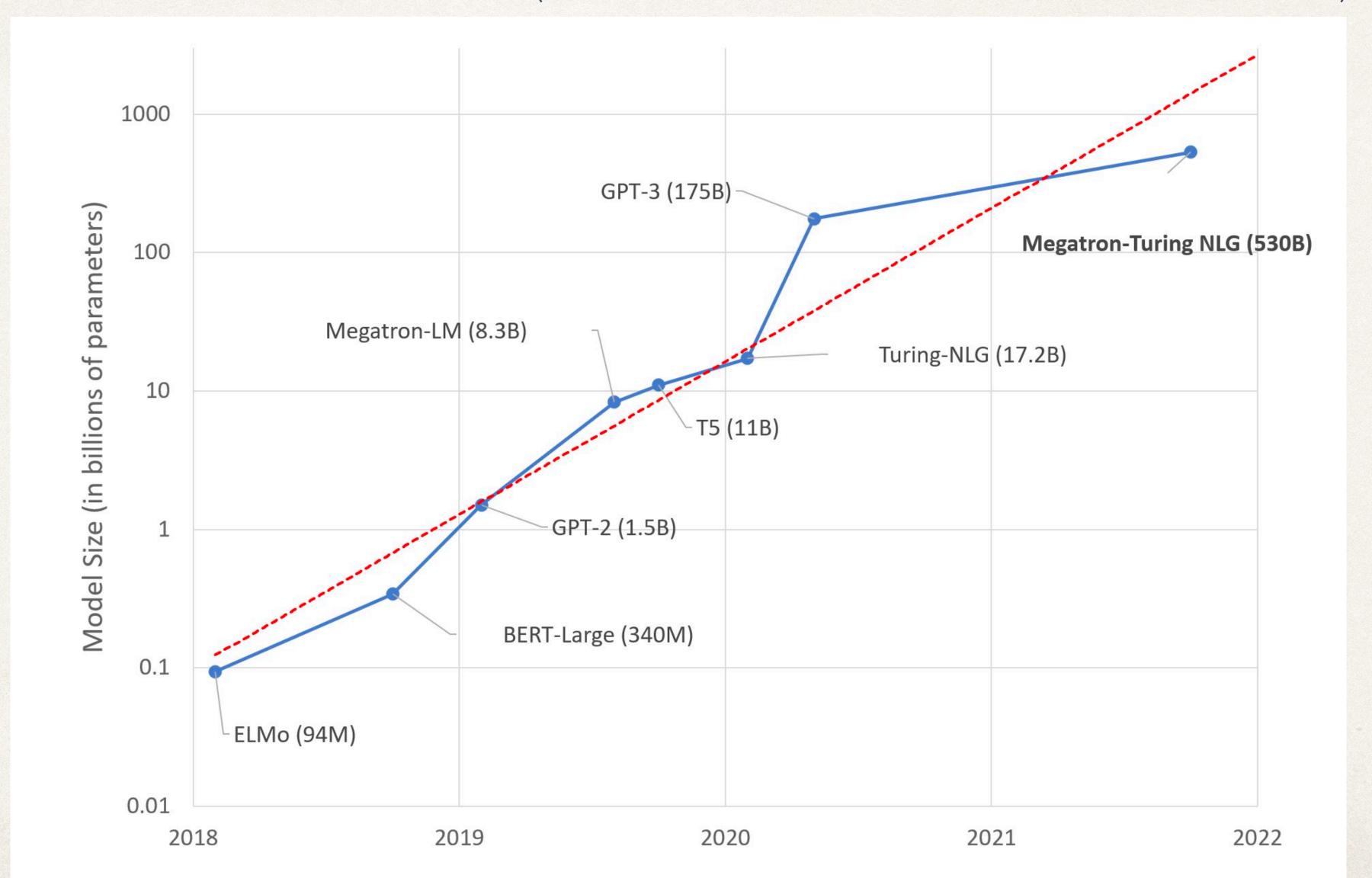
 $i_t \sim \text{Uniform}(1, |data|)$ 

$$\mathbf{x}_{t+1} := \mathbf{x}_t - \gamma_t \nabla f_{i_t}(\mathbf{x}_t)$$

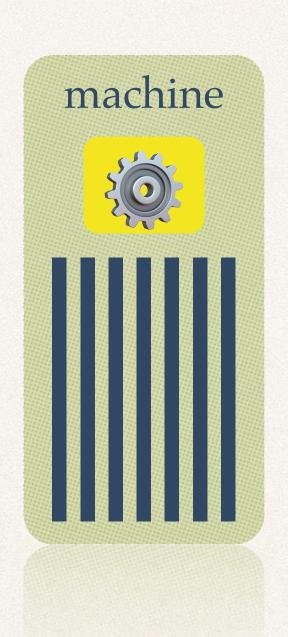




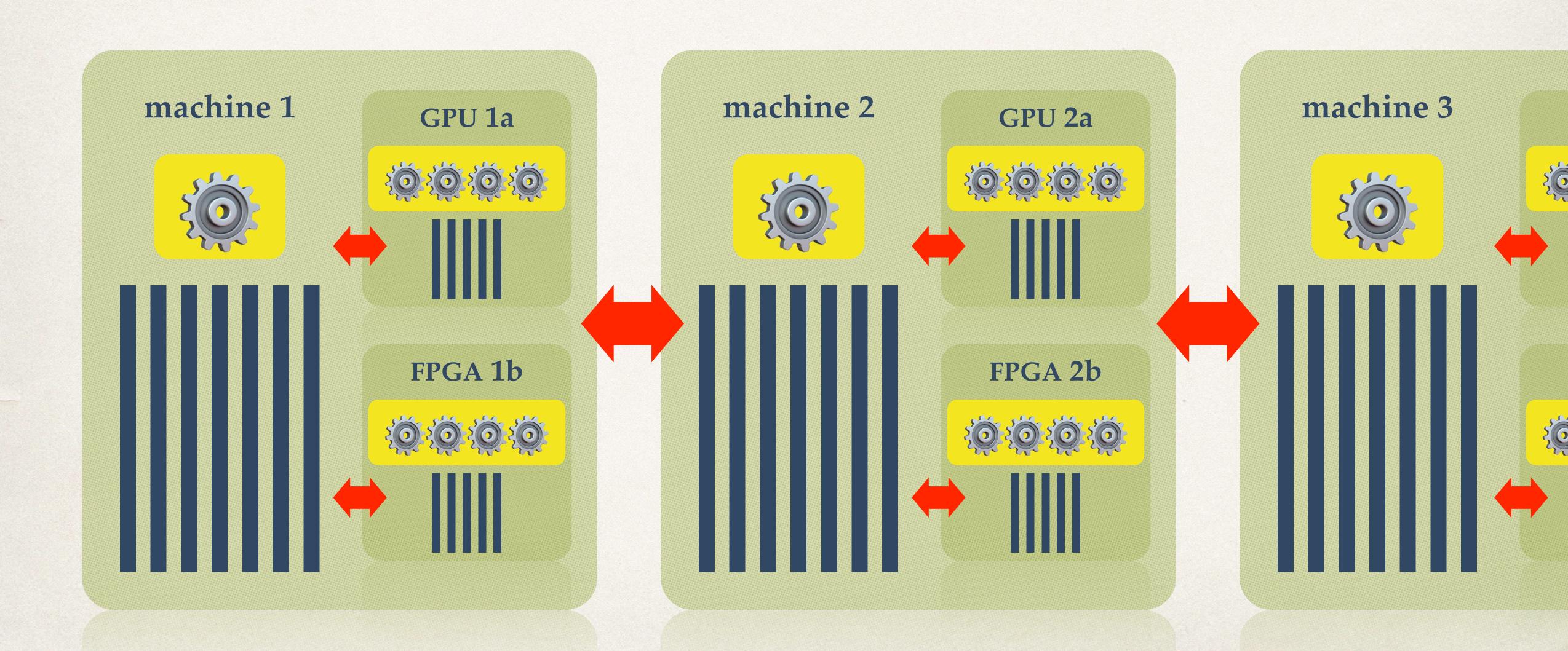
#### Model Sizes (Transformer Models)



## Systems ...then



#### Systems ...now

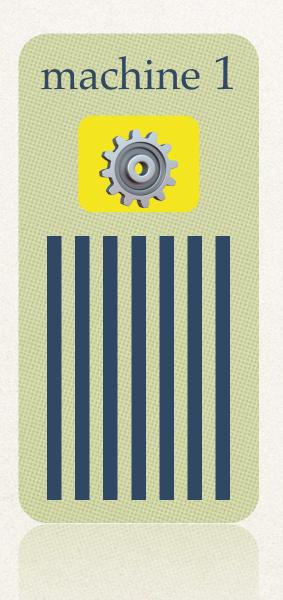


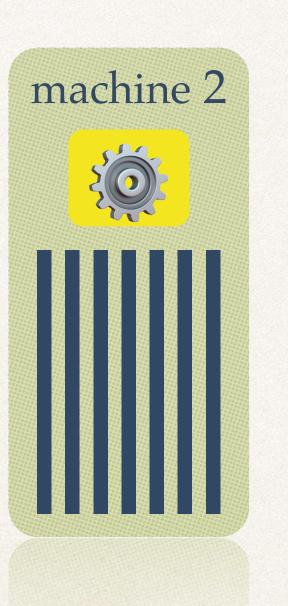
# What are the fundamental limits of parallelizing the training of neural networks?

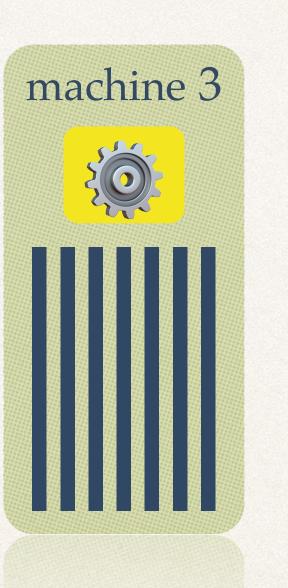


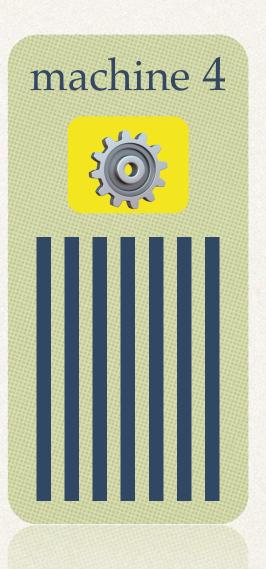
### Parallel & Distributed Training

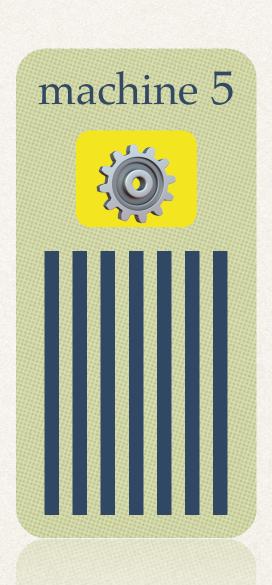
Distribute compute & memory across many devices



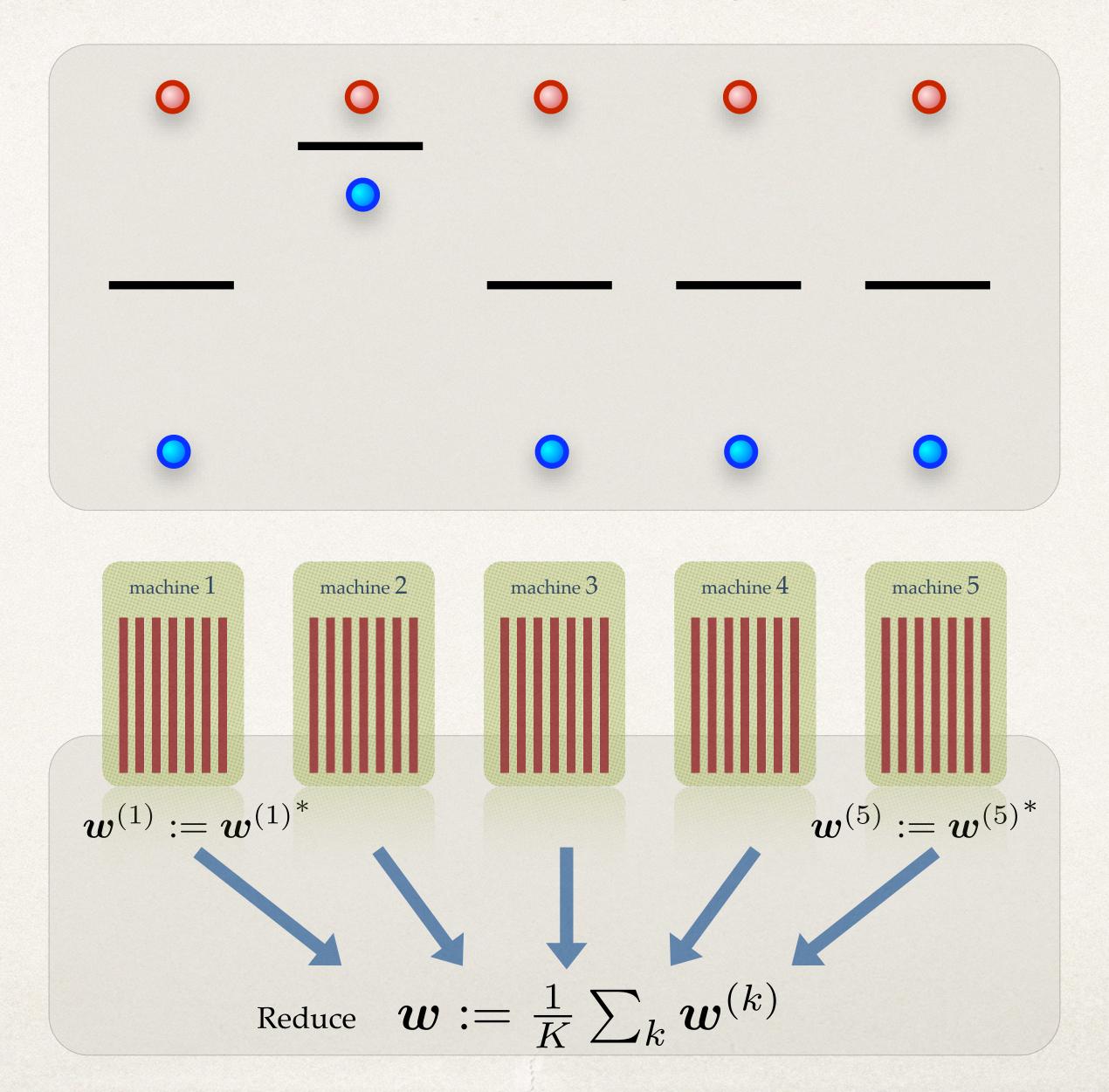




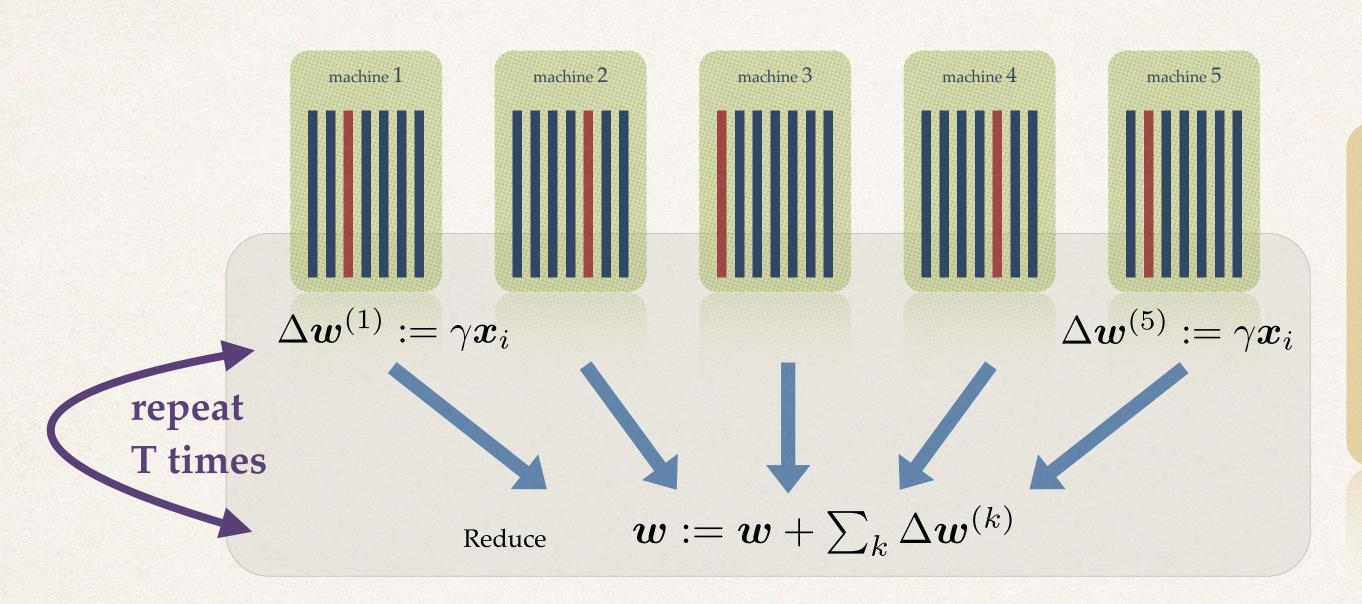




#### One-Shot Model Averaging Does Not Work

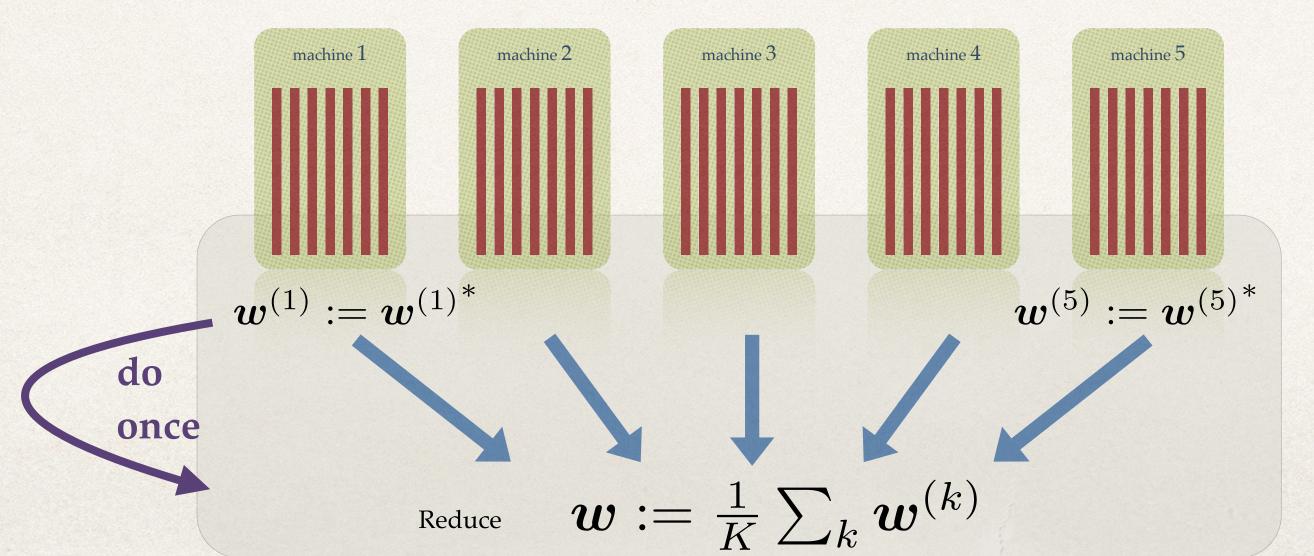


## Communication: Always / Never



#### **Naive Distributed SGD**

"always communicate"

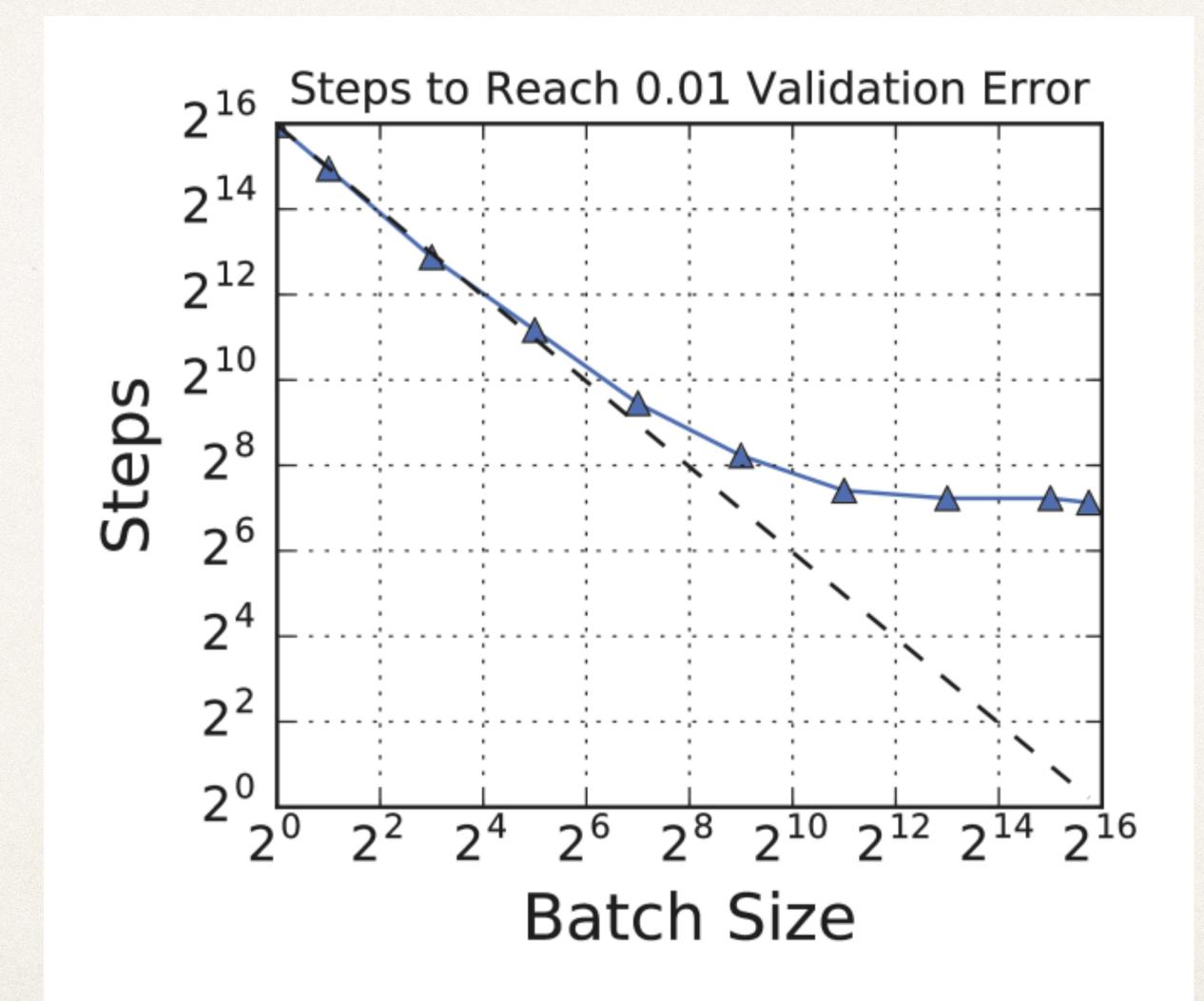


#### One-Shot Averaged Distributed Optimization

#local datapoints read:T
#communications: 1
convergence: \*\*

"never communicate"

#### Just increase the batch size!



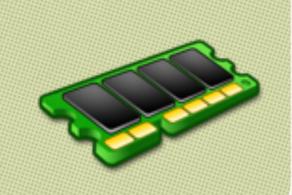


#### The Cost of Communication

 $oldsymbol{v} \in \mathbb{R}^{100}$ 

\* Reading v from memory (RAM)

100 ns

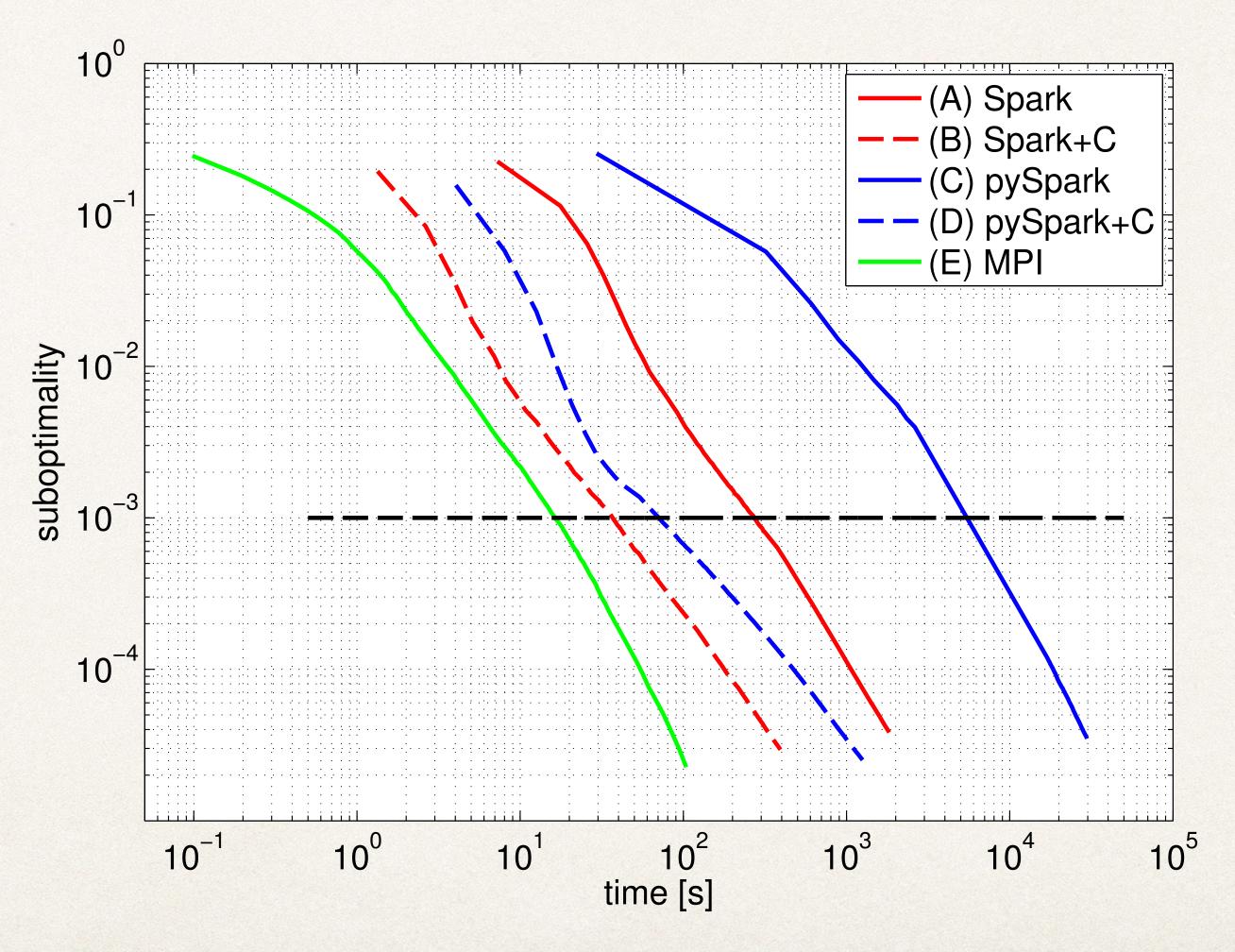


- Sending v to another machine 500'000 ns
- \* Typical Map-Reduce iteration 10'000'000'000 ns



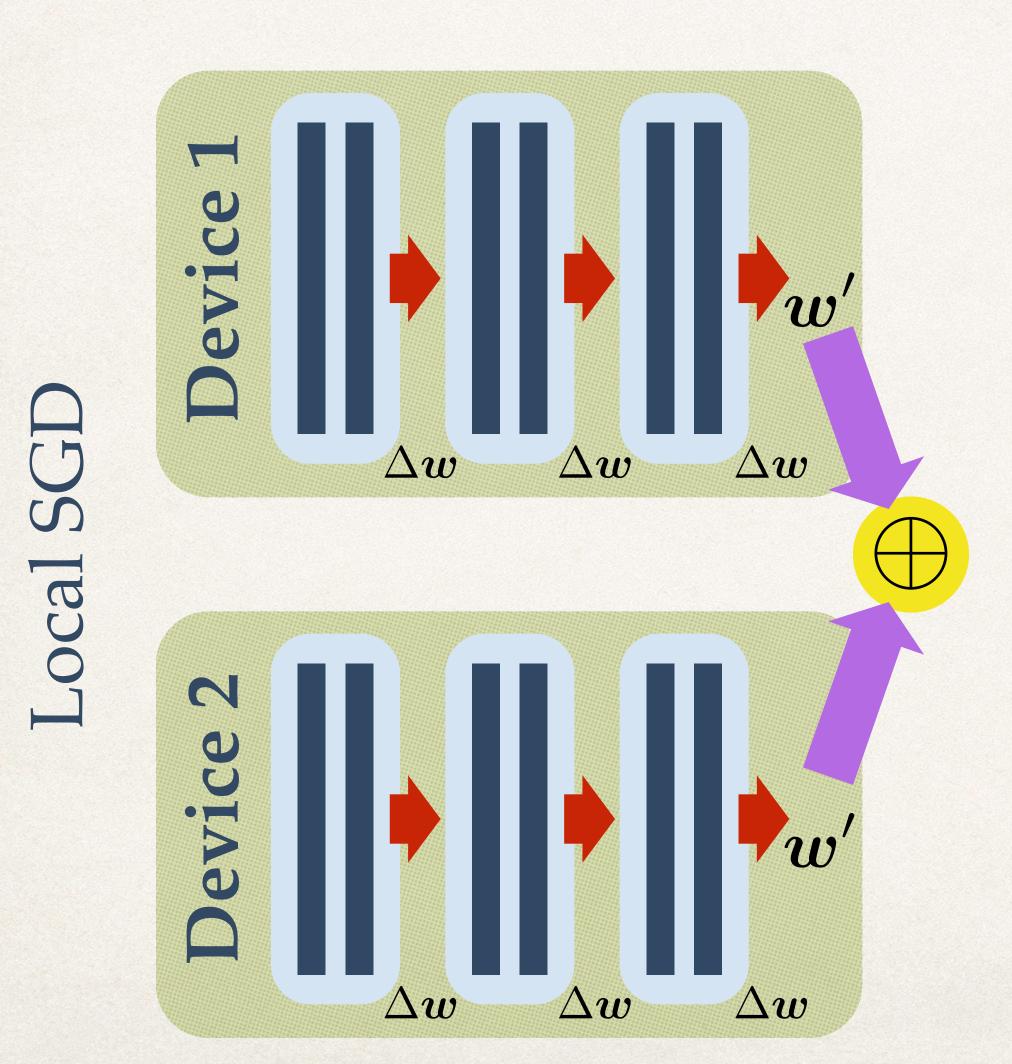


#### The Cost of Communication

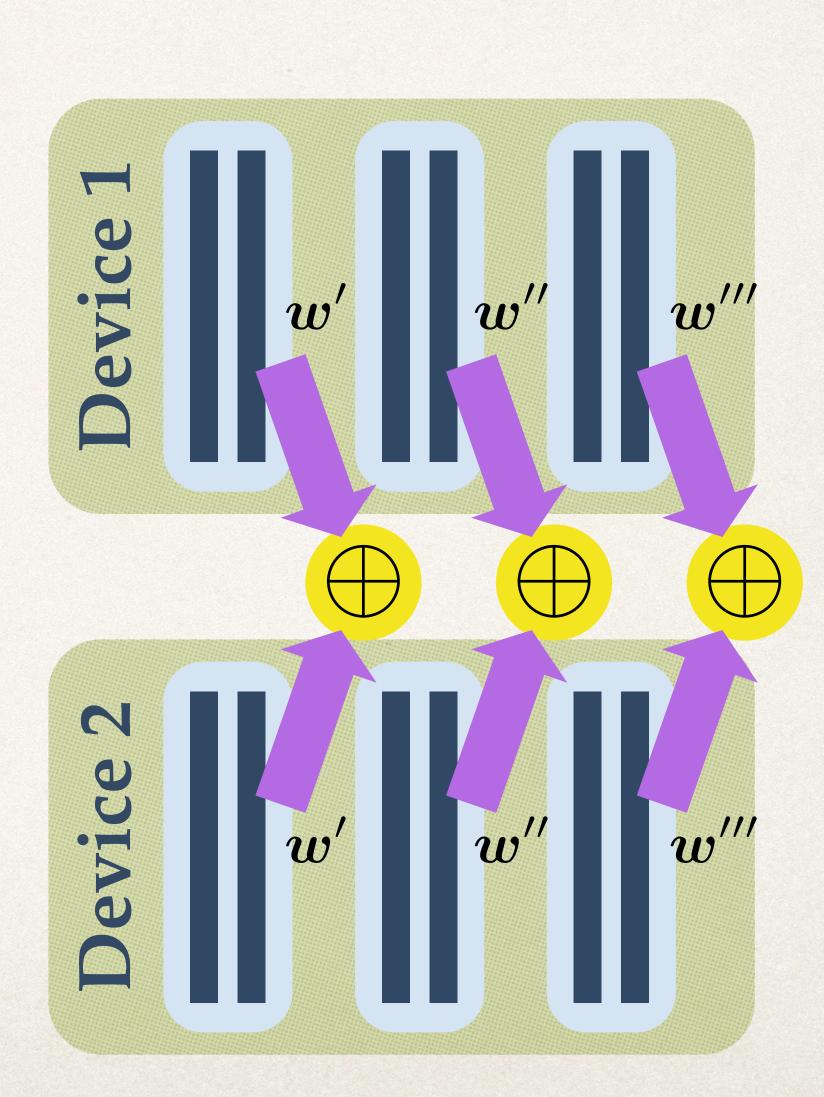


High-Performance Distributed Machine Learning using Apache Spark Dünner et al. 2016, <a href="mailto:arxiv.org/abs/1612.01437">arxiv.org/abs/1612.01437</a>

#### Data Parallel DL, Local Update Steps



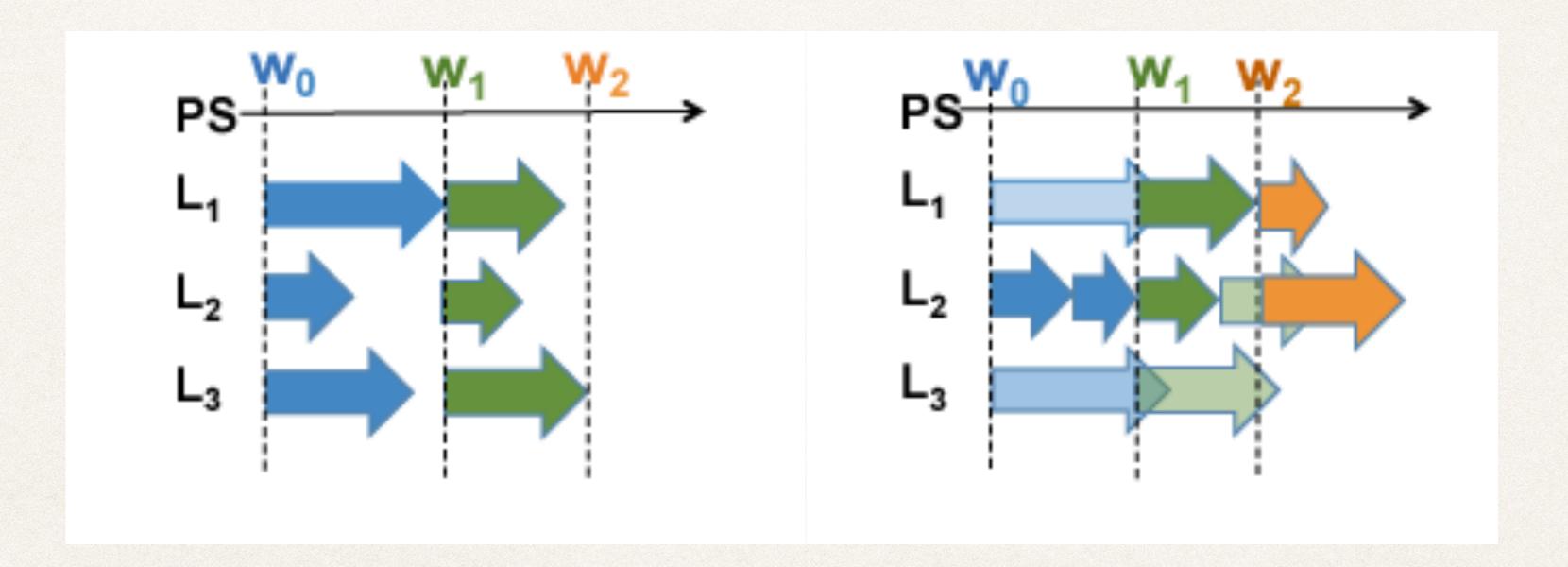
Mini-batch SGD



#### Asynchronous Parallel SGD

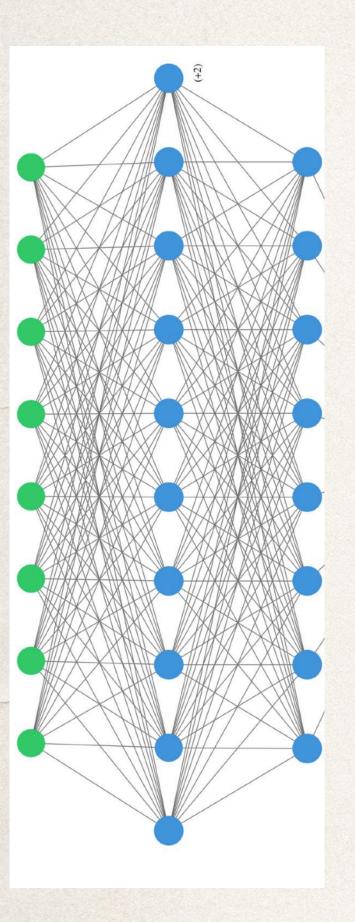
\* Synchronous

\* Asynchronous



Mini-Batch!

### Communication Compression



A compressed version of model updates?

#### **Examples:**

#### Communication

Reduction

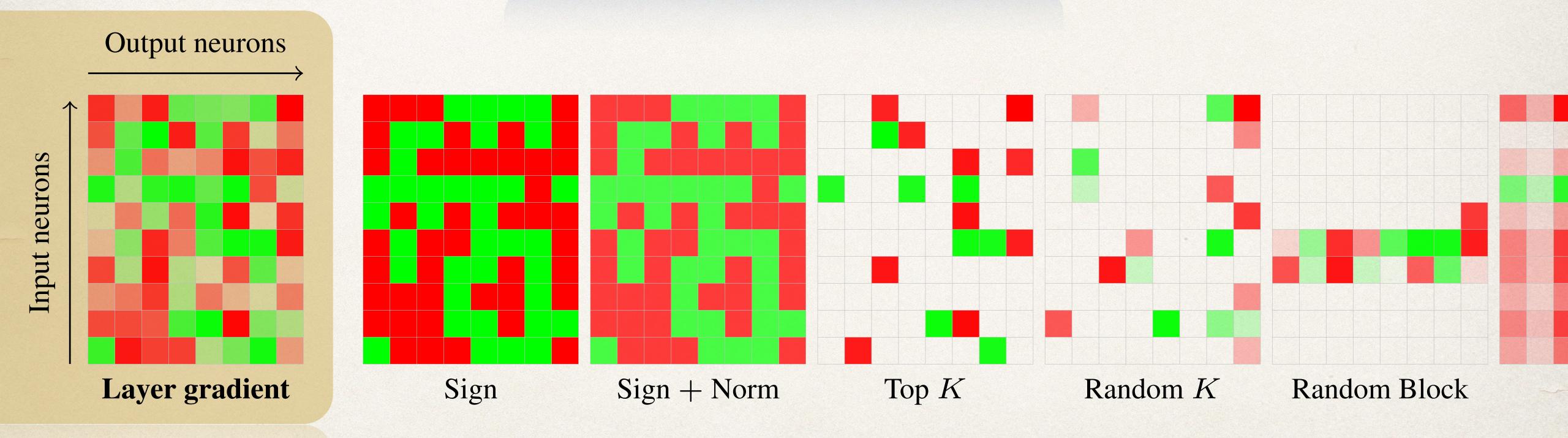
quantization (e.g. 1-bit SGD)

\* top k=1% of all the entries 100x

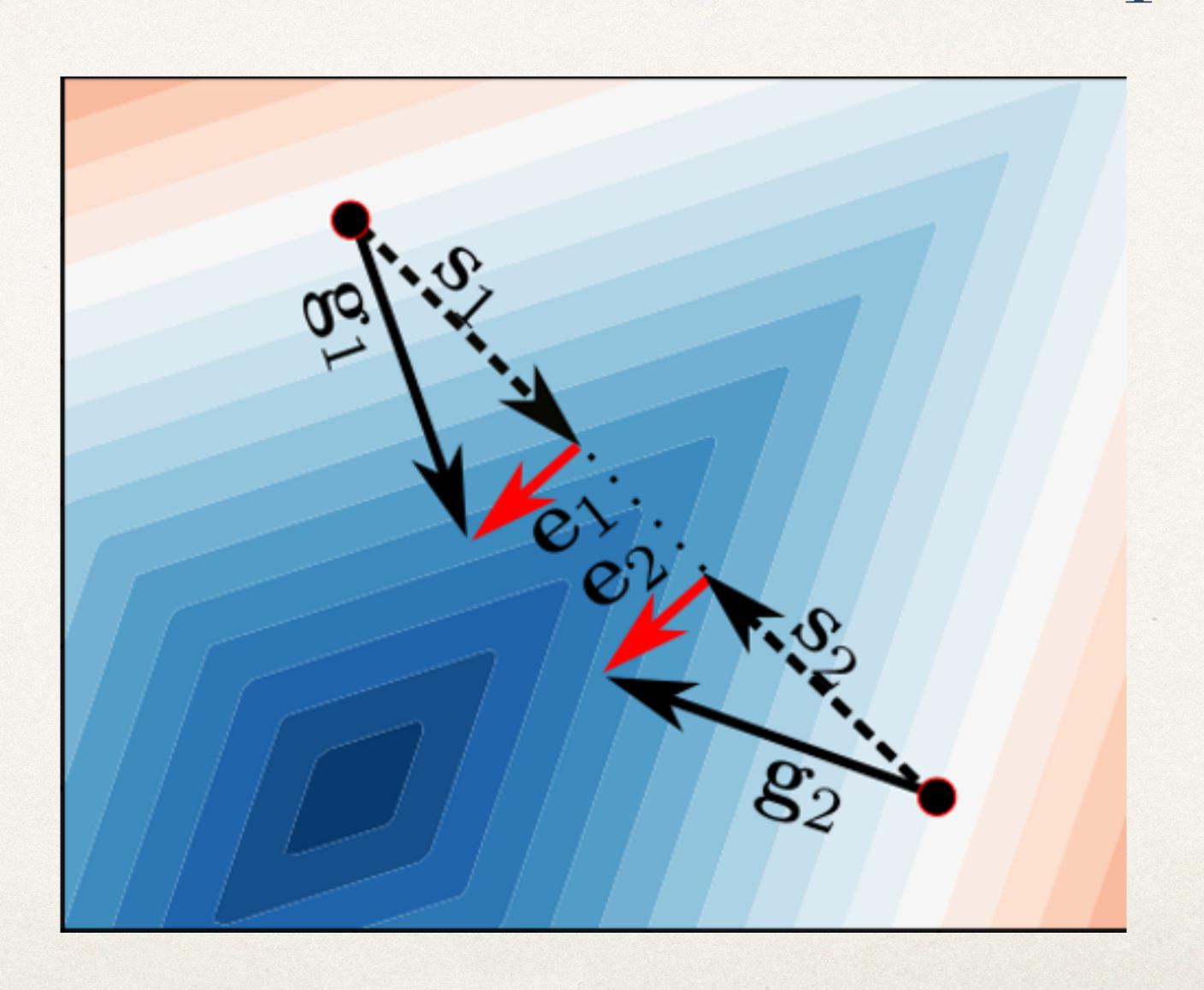
\* rank-1 approximation >100x

## Gradient Compression

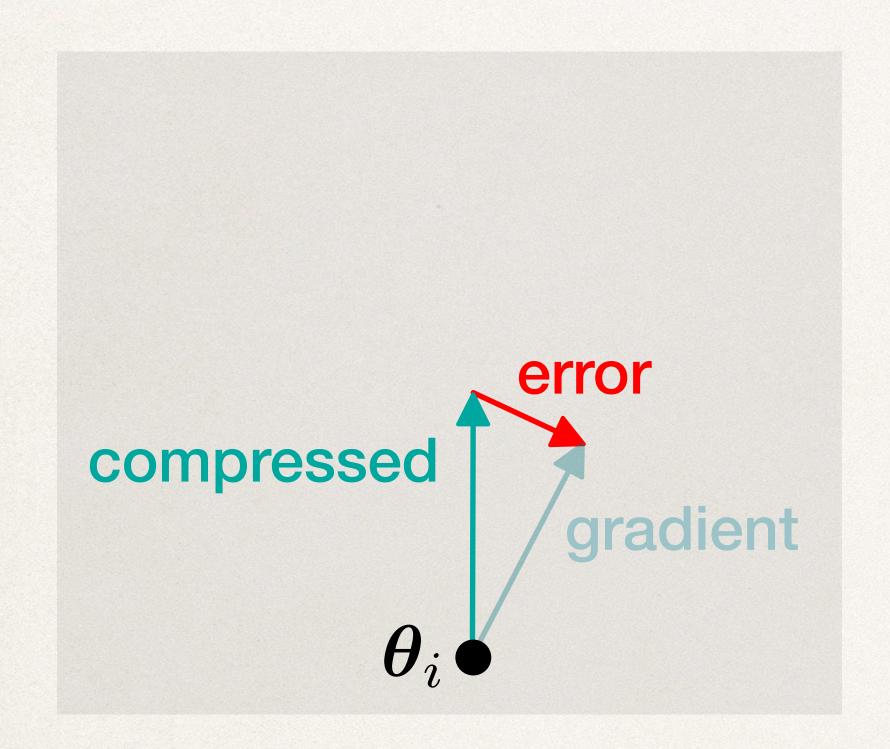
A compressed version of model updates?



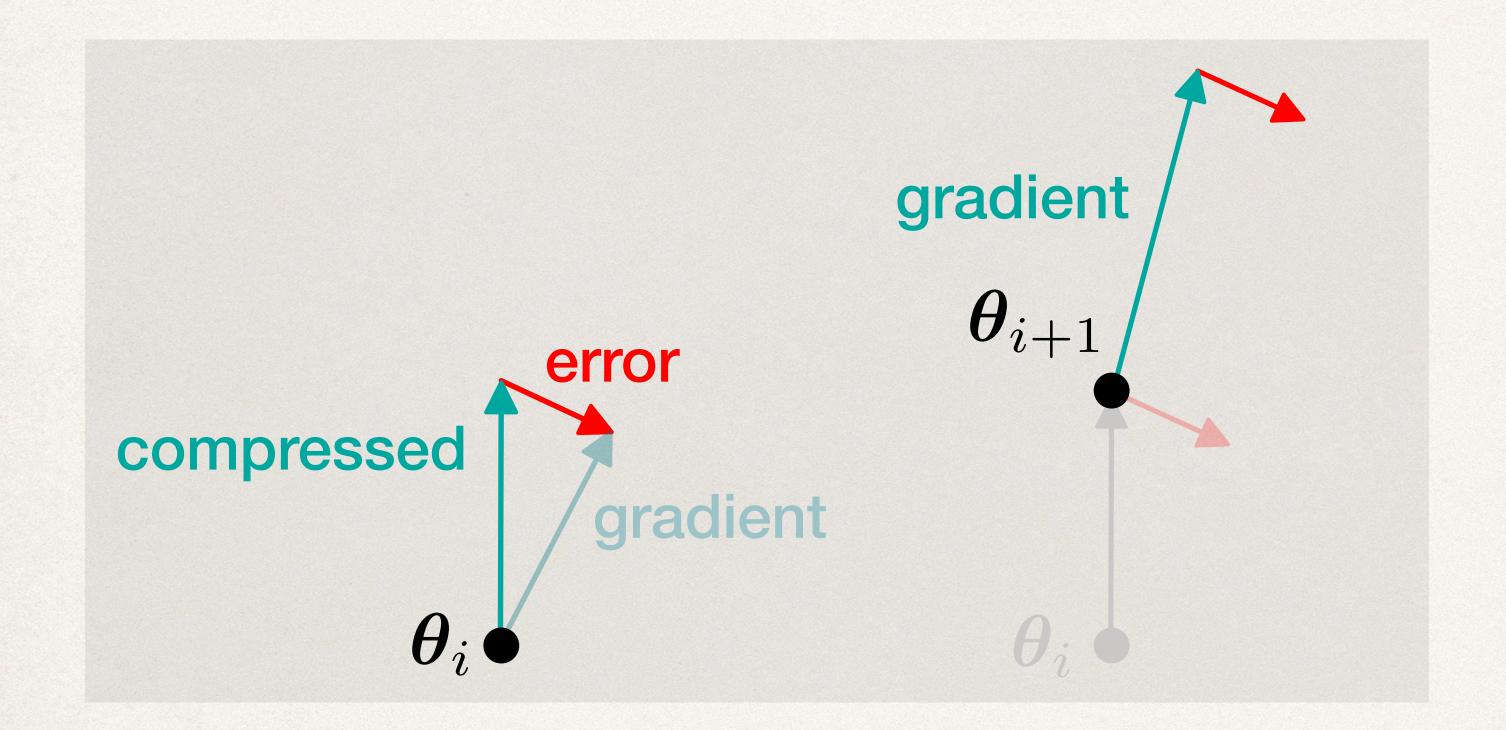
## SGD fails with naive/biased compressors.



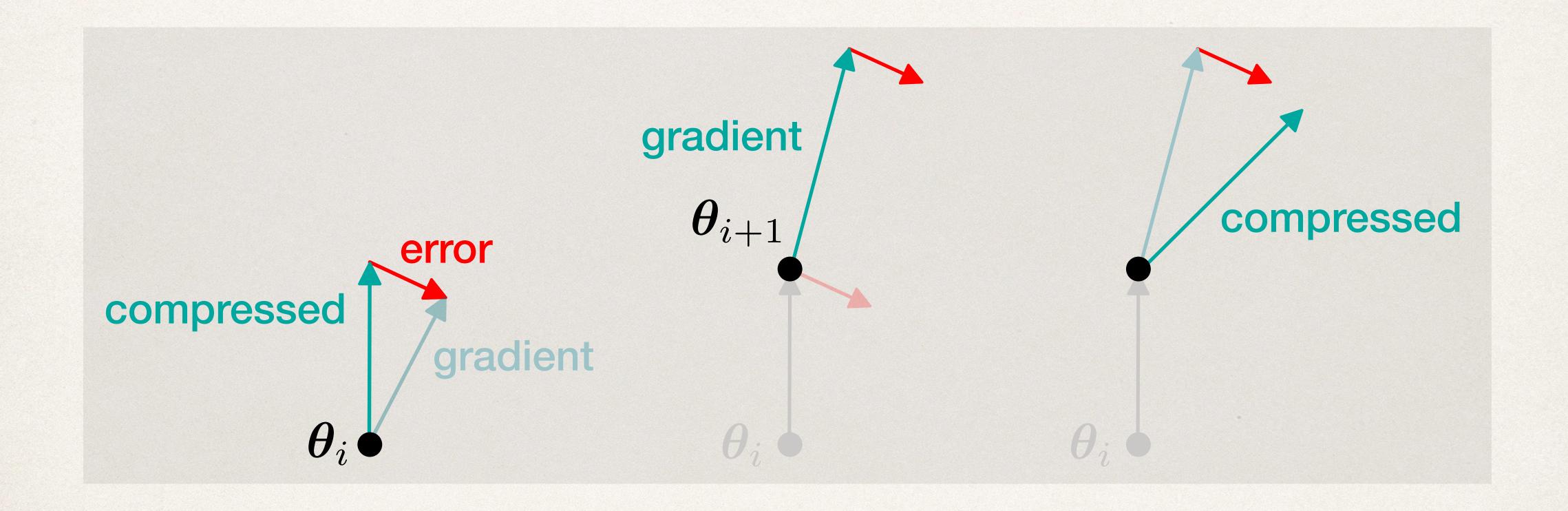
#### Error Feedback



#### Error Feedback



#### Error Feedback



## Error Feedback: Convergence Rate

 $\delta$ : compression ratio

$$\|\mathcal{C}(\mathbf{x}) - \mathbf{x}\|_{2}^{2} \le (1 - \delta) \|\mathbf{x}\|_{2}^{2}$$

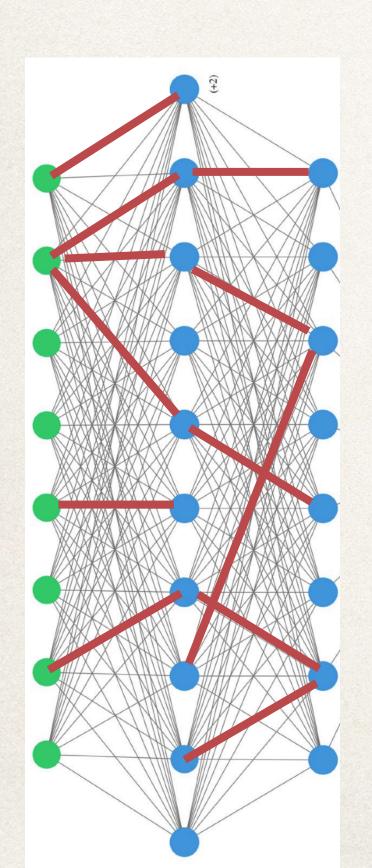
SGD on smooth non-convex objectives (w/central coordinator)

$$\mathbb{E}\|\nabla f(\bar{x}_t)\|^2 \le \mathcal{O}\left(\frac{1}{\sqrt{nT}} + \frac{1}{\delta^2 T}\right)$$

#### Can we also save Compute and Memory?

e.g. for deployment on low-resource devices

#### Model Compression with Error Feedback



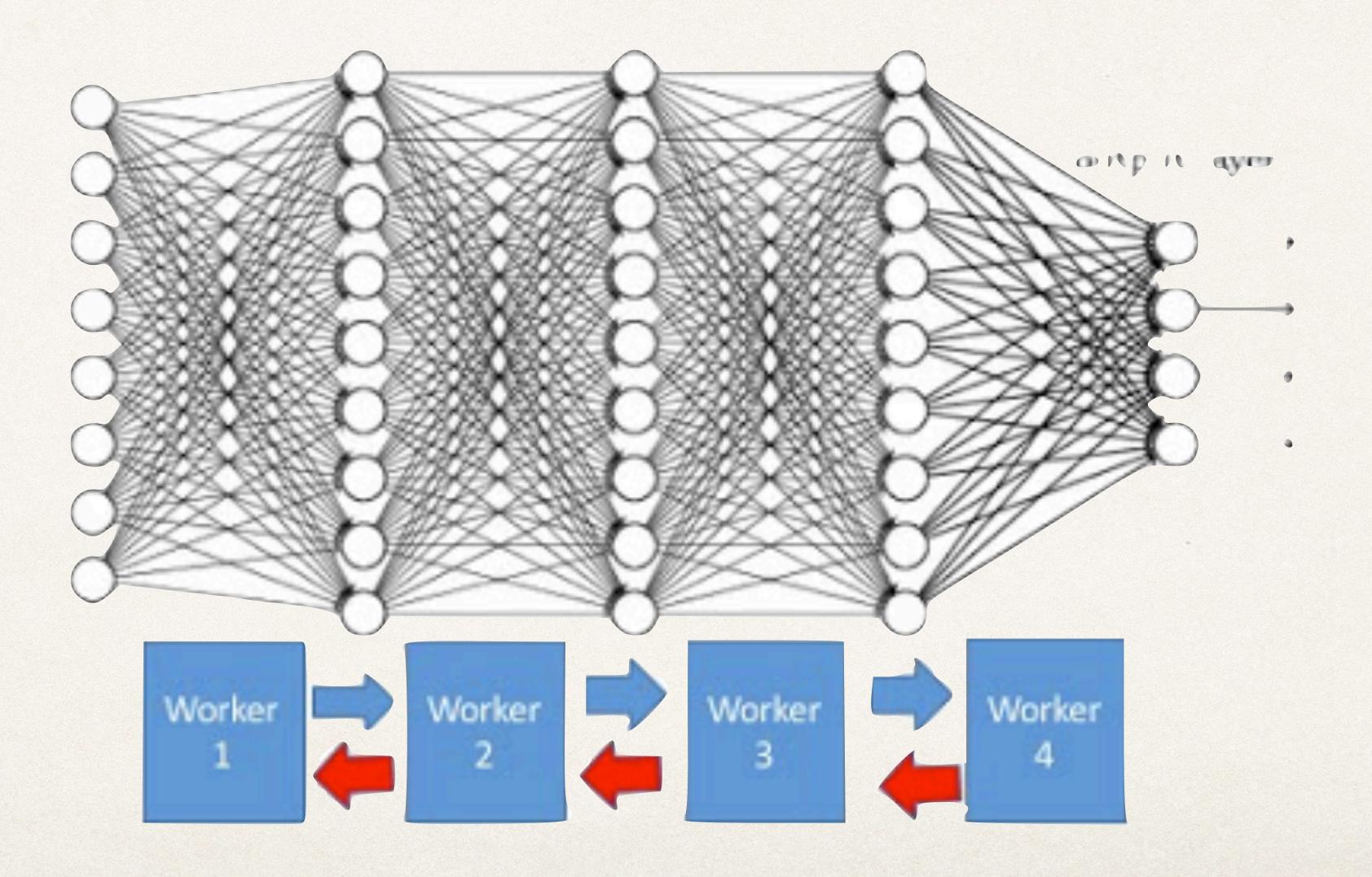
Prune most weights (set to zero)

set to limited precision

interactive while training

#### (Model Parallel)

#### Model-Parallel DL



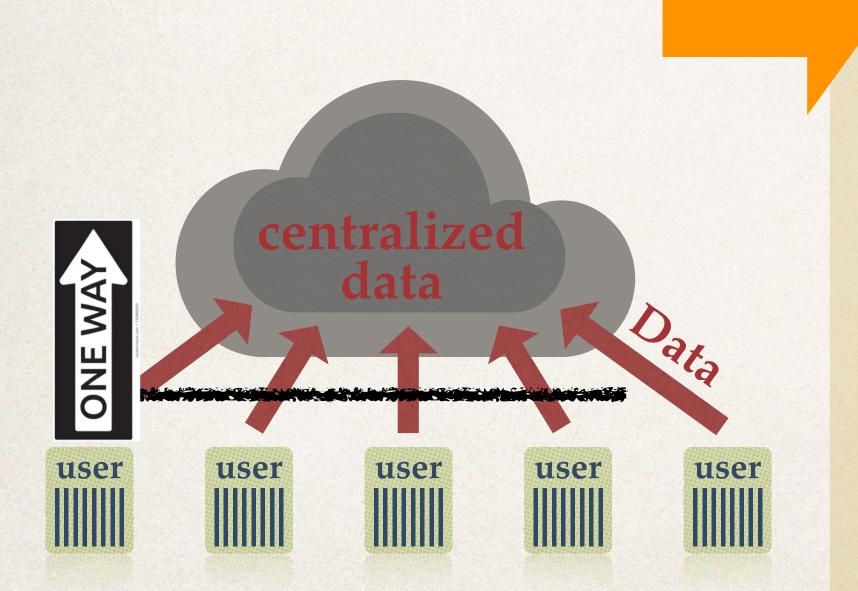
## Gradients from collaborators: - Federated Learning

## Collaborative & Federated Learning

Distributed, Collaborative Learning

#### centralized

traditional, sharing data

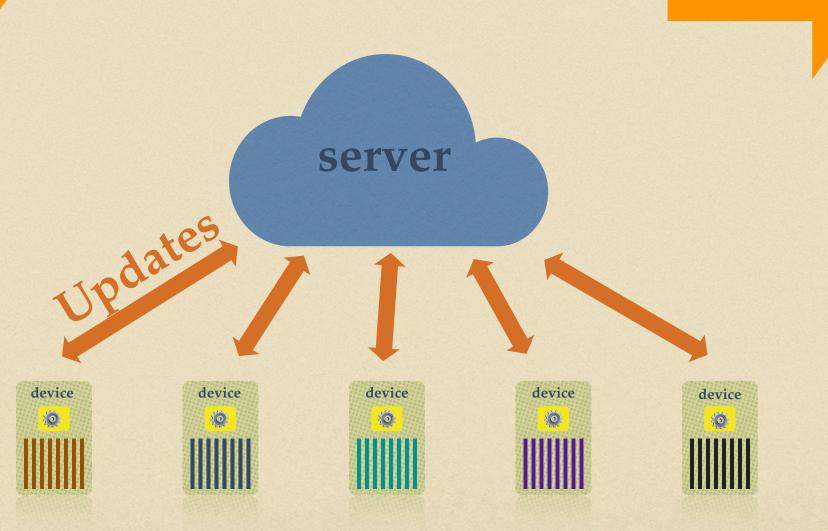


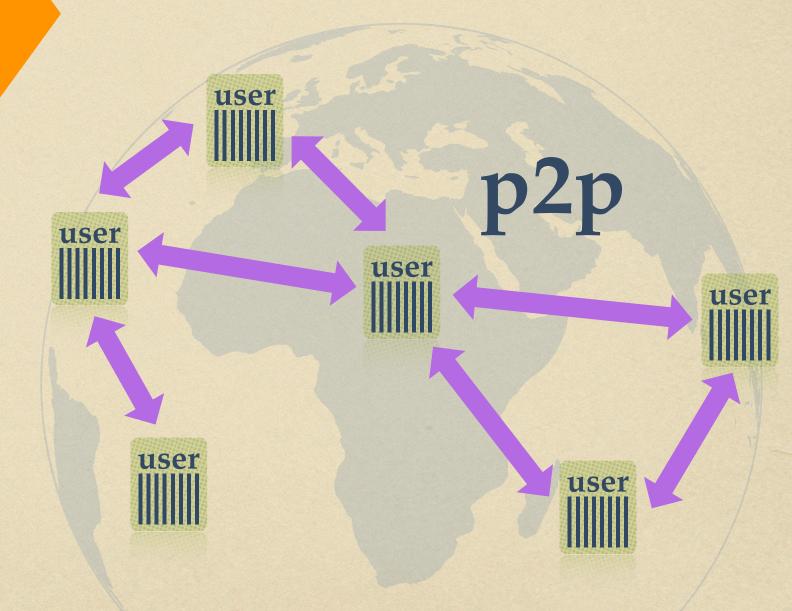
#### federated

sharing model updates

#### decentralized

learning





Thanks!

mlo.epfl.ch tml.epfl.ch